



TRANSMISSION APPARATUS, RECEPTION APPARATUS AND DIGITAL RADIO COMMUNICATION METHOD

Cross Reference to Related Application

This application is a continuation of U.S. Patent Application No. 09/627,070, filed on July 27, 2000, the content of which is hereby incorporated herein by reference in its entirety.

BACKGROUND OF THE INVENTION

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Field of the Invention

The present invention relates to a transmission apparatus, reception apparatus and digital radio communication method, which is used for digital radio
10 communications.

Description of the related Art

As a conventional digital modulation system, a technology described in the Unexamined Japanese Patent
15 Publication No. HEI 1-196924 is known. This is the technology which the transmitting side configures a frame by inserting 1 known pilot symbol for every N data symbols and the receiving side estimates a frequency offset and amount of amplitude distortion by using the
20 pilot symbol, and removes these frequency offset and amplitude distortion and demodulates.

Here, in the case of a radio communication, fluctuations in the transmission path occur due to fading and in terrestrial mobile communication in particular,
25 fluctuations in the transmission path are not uniform. When fluctuations in the transmission path are intense, the interval of inserting a pilot symbol must be shorter to prevent deterioration of the data demodulation error

5 On the other hand, when the level of a reception
signal on the receiving side is small, a modulation
system used must be highly resistant to errors for
information symbols. On the contrary, when the level of
a reception signal on the receiving side is large, higher
10 priority can be given to a modulation system of high
transmission efficiency for information symbols.

However, in the conventional digital modulation system above, the pilot symbol insertion interval and the information symbol modulation system are fixed.

15 Therefore, when fluctuations in the transmission path are intense or the level of the reception signal of the receiver is small, error resistance during data demodulation reduces and the quality of data deteriorates. On the other hand, when fluctuations in

20 the transmission path are gentle or the level of the reception signal on the receiving side is large, the data transmission efficiency cannot be improved despite the excessive data quality.

It is an object of the present invention to provide a transmission apparatus, reception apparatus and digital radio communication method capable of flexibly

improving the data transmission efficiency and the quality of data.

The present invention attains the above object by changing the interval of inserting a known pilot symbol,
5 binary phase (BPSK: Binary Phase Shift Keying) modulation symbols or quadrature phase (QPSK: Quadrature Phase Shift Keying) modulation symbols and the modulation system of information symbols according to the communication situation such as fluctuations in the
10 transmission path and the level of a reception signal.

BRIEF DESCRIPTION OF THE DRAWINGS

The above and other objects and features of the invention will appear more fully hereinafter from a
15 consideration of the following description taken in connection with the accompanying drawing wherein one example is illustrated by way of example, in which;

FIG.1 is a block diagram showing a configuration of a transmission apparatus according to Embodiment 1
20 of the present invention;

FIG.2 illustrates examples of a frame configuration of a signal transmitted from the transmission apparatus of Embodiment 1 of the present invention;

25 FIG.3 is a layout of signal points of 16QAM and a known pilot symbol on an in-phase I - quadrature Q plane;

FIG.4 is a layout of signal points of 8PSK modulation and a known pilot symbol on an in-phase I -

quadrature Q plane;

FIG.5 is a block diagram showing a configuration of a reception apparatus according to Embodiment 1 of the present invention;

5 FIG.6 is a block diagram showing a configuration of a transmission apparatus according to Embodiment 2 of the present invention;

FIG.7 illustrates examples of a frame configuration of a signal transmitted from the
10 transmission apparatus of Embodiment 2 of the present invention;

FIG.8 is a layout of signal points of 16QAM and BPSK modulation on an in-phase I - quadrature Q plane;

FIG.9 is a layout of signal points of 8PSK
15 modulation and BPSK modulation on an in-phase I - quadrature Q plane;

FIG.10 is a block diagram showing a configuration of a reception apparatus according to Embodiment 2 of the present invention;

20 FIG.11 is a block diagram showing a configuration of a transmission apparatus according to Embodiment 3 of the present invention;

FIG.12 illustrates examples of a frame configuration of a signal transmitted from the
25 transmission apparatus of Embodiment 3 of the present invention;

FIG.13 is a layout of signal points of 16QAM and QPSK modulation on an in-phase I - quadrature Q plane;

FIG.14 is a layout of signal points of 8PSK modulation and QPSK modulation on an in-phase I - quadrature Q plane;

FIG.15 is a block diagram showing a configuration of a reception apparatus according to Embodiment 3 of the present invention;

FIG.16 is a block diagram showing a configuration of a transmission apparatus according to Embodiment 4 of the present invention;

FIG.17 illustrates examples of a frame configuration of a signal transmitted from the transmission apparatus of Embodiment 4 of the present invention;

FIG.18 is a layout of signal points of BPSK modulation on an in-phase I - quadrature Q plane;

FIG.19 is a layout of signal points of QPSK modulation on an in-phase I - quadrature Q plane;

FIG.20 is a block diagram showing a configuration of a reception apparatus according to Embodiment 4 of the present invention;

FIG.21 is a block diagram showing a configuration of a transmission apparatus according to Embodiment 5 of the present invention;

FIG.22 illustrates examples of a frame configuration of a signal transmitted from the transmission apparatus of the Embodiment 5 of the present invention;

FIG.23 is a layout of signal points of 16QAM, a known

pilot symbol and symbols before and after the pilot symbol on an in-phase I - quadrature Q plane;

FIG.24 is a layout of signal points of 8PSK modulation, a known pilot symbol and symbols before and after the pilot symbol on an in-phase I - quadrature Q plane; and

FIG.25 is a block diagram showing a configuration of a reception apparatus according to Embodiment 5 of the present invention.

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DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

With reference now to the attached drawings, embodiments of the present invention will be explained in detail below.

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(Embodiment 1)

Embodiment 1 describes a digital radio communication method by which the interval of inserting a known pilot symbol and the modulation system of information symbols are changed according to the communication situation.

FIG.1 is a block diagram showing a configuration of a transmission apparatus according to this embodiment. As shown in FIG.1, the transmission apparatus according to this embodiment mainly consists of frame configuration determination section 101, quadrature baseband modulation section 102, pilot symbol

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generation section 103, frame configuration section 104, and LPFs(Low Pass Filters)105 and 106, transmission radio section 107 and transmission antenna 108.

Frame configuration determination section 101
5 judges the communication situation based on transmission path information which shows the degree of fluctuations of the transmission path due to fading and data transmission speed information which shows the transmission speed of transmission data based on the
10 level of a reception signal and decides the interval of inserting a known pilot symbol and the modulation system of a transmission digital signal. Then, frame configuration determination section 101 outputs a signal indicating the determined modulation system to
15 quadrature baseband modulation section 102 and outputs a signal indicating the determined interval of inserting the known pilot symbol to frame configuration section 104. By the way, details of the method of determining a frame configuration by frame configuration
20 determination section 101 will be described later.

Here, when an identical frequency band is used for the uplink and the downlink, the situation of fluctuations in the transmission path due to fading can be estimated from a transition in the result of measuring
25 the reception level of the modulated signal transmitted from the other end of communication on the receiving side, which is not shown in the figure, of the communication apparatus in which the transmission

apparatus shown in FIG.1 is mounted. Furthermore, the transmission apparatus shown in FIG.1 can recognize the situation of fluctuations in the transmission path due to fading, by the reception apparatus, which is the other end of communication of the transmission apparatus shown in FIG.1, measuring the reception level of the modulated signal transmitted from the other end of communication, estimating the situation of fluctuations in the transmission path due to fading based on the transition of the measurement result.

Then, when an identical frequency band is used for the uplink and the downlink, the transmission speed of the transmission data can be determined from a result of measuring the reception level of the modulated signal transmitted from the other end of communication on the receiving side, which is not shown in the figure, of the communication apparatus in which the transmission apparatus shown in FIG.1 is mounted. Furthermore, the transmission apparatus shown in FIG.1 can recognize the transmission speed of the transmission data by the reception apparatus, which is the other end of communication of the transmission apparatus shown in FIG.1, measuring the reception level of the pilot symbol transmitted from the other end of communication and determining the transmission speed of the transmission data based on the measurement result.

Quadrature baseband modulation section 102 modulates a transmission digital signal to a quadrature

baseband signal with the modulation system indicated from frame configuration determination section 101 and outputs the in-phase component and the quadrature component of the quadrature baseband signal to frame
5 configuration section 104.

Pilot symbol generation section 103 generates a pilot symbol known between the transmitting and receiving sides and outputs the in-phase component and the quadrature component of the known pilot symbol to
10 frame configuration section 104.

Frame configuration section 104 inserts the known pilot symbol output from pilot symbol generation section 103 into the output signal of quadrature baseband modulation section 102 at the insertion interval
15 instructed from frame configuration determination section 101 and composes a frame.

LPF 105 lets pass only a predetermined frequency band section of the in-phase component output from frame configuration section 104. LPF 106 lets pass only a
20 predetermined frequency band section of the quadrature component output from frame configuration section 104.

Transmission radio section 107 transmits a radio frequency signal as the electric wave from transmission antenna 108 after performing radio processing on the
25 output signals of LPF 105 and LPF 106.

Next, examples of the method of determining a frame configuration by frame configuration determination section 101 of the transmission apparatus shown in FIG.1

above will be explained.

FIG.2 illustrates examples of a frame configuration of a signal transmitted from the transmission apparatus of this embodiment and shows a time-symbol relationship. (201) is a frame configuration when the modulation system of information symbols is 16-value quadrature amplitude modulation (16QAM: 16 Quadrature Amplitude Modulation) and a known pilot symbol interval is N symbols. (202) is a frame configuration when the modulation system of information symbols is 16QAM and a known pilot symbol interval is M symbols. (203) is a frame configuration when the modulation system of information symbols is 8 phases (8PSK: 8 Phase Shift Keying) modulation and a known pilot symbol interval is N symbols. (204) is a frame configuration when the modulation system of information symbols is 8PSK modulation and a known pilot symbol interval is M symbols. Suppose $N < M$ at this time.

Frame configuration determination section 101 selects one of (201), (202), (203) or (204) in FIG.2 as the optimal frame configuration based on the transmission path information and the request data transmission speed information.

For example, in the case of high-speed fading, frame configuration determination section 101 sacrifices data transmission efficiency on the receiving side and selects a frame configuration of either (201) or (203) in FIG.2 so that the interval of inserting a known pilot

symbol becomes narrower to prevent deterioration of the data demodulation error rate and maintain the quality of data. On the other hand, in the case of low-speed fading, frame configuration determination section 101
5 selects a frame configuration of either (202) or (204) in FIG.2 to widen the interval of inserting a known pilot symbol to improve the data transmission efficiency.

Also, when the level of the reception signal is large, frame configuration determination section 101
10 gives priority to data transmission efficiency on the receiving side and selects a frame configuration of either (201) or (202) in FIG.2 adopting 16QAM as the modulation system of information symbols. On the other hand, when the level of the reception signal is small,
15 frame configuration determination section 101 gives priority to increasing error resistance while sacrificing data transmission efficiency on the receiving side and selects a frame configuration of either (203) or (204) in FIG.2 adopting 8PSK as the
20 modulation system of information symbols.

FIG.3 shows a signal point layout according to the 16QAM modulation system on the in-phase I - quadrature Q plane and signal point layout of a known pilot symbol. Signal point 301 is the signal point of a known pilot
25 symbol and signal points 302 are the signal points of 16QAM modulation symbols. FIG.4 shows a signal point layout according to the 8PSK modulation system on the in-phase I - quadrature Q plane and signal point layout

of a known pilot symbol. Signal point 401 is the signal point of a known pilot symbol and signal points 402 are the signal points of 8PSK modulation symbols.

FIG.5 is a block diagram showing a configuration of the reception apparatus according to this embodiment. As shown in FIG.5, the reception apparatus according to this Embodiment mainly consists of reception antenna 501, reception radio section 502, transmission path distortion estimation section 503 and detection section 504.

Reception radio section 502 receives the radio signal received by reception antenna 501 as an input, performs predetermined radio processing and outputs the in-phase component and the quadrature component of the reception quadrature baseband signal.

Transmission path distortion estimation section 503 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, extracts the signal of the known pilot symbol shown in FIG.3 and FIG.4 above, estimates the amount of transmission path distortion from the reception condition of the known pilot symbol and outputs the amount of transmission path distortion to detection section 504.

Detection section 504 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, detects information symbols based on the amount of transmission path distortion and

outputs a reception digital signal.

Thus, changing the interval of inserting a known pilot symbol and the modulation system of information symbols according to the communication situation such as fluctuations in the transmission path and the level of the reception signal can improve both the data transmission efficiency and the quality of data at the same time.

Here, this embodiment explains two kinds of the interval of inserting a known pilot symbol, but the present invention is not limited to this. Furthermore, this embodiment explains two kinds of the modulation system of information symbols, 16QAM and the 8PSK modulation, but the present invention is not limited to this.

Furthermore, this embodiment only explains the frame configuration of information symbols and a known pilot symbol shown in FIG.2, but since it is also possible to consider a frame configuration in which signals such as a symbol for synchronization to adjust timing between the receiver and transmitter and a symbol to correct an error on the receiver side are inserted, the present invention is not limited to the frame configuration composed of only information symbols and known pilot symbol.

(Embodiment 2)

Embodiment 2 describes a digital radio

communication method by which the interval of inserting
a BPSK modulation symbol and the modulation system of
information symbols other than the above BPSK modulation
symbol are changed according to the communication
5 situation.

FIG. 6 is a block diagram showing a configuration
of the transmission apparatus according to this
Embodiment. Here, in the transmission apparatus shown
in FIG.6, the components common to those in the
10 transmission apparatus shown in FIG.1 are assigned the
same reference numerals as those in FIG.1 and their
explanations will be omitted.

In the transmission apparatus in FIG.6, frame
configuration determination section 601 differs in the
15 way of operation from the frame configuration
determination section 101 in FIG.1. Also, when compared
to FIG.1, the transmission apparatus in FIG.6 adopts the
configuration with BPSK symbol modulation section 602,
instead of pilot symbol generation section 103, added.

20 Frame configuration determination section 601
judges the communication situation, determines the
interval of inserting a BPSK modulation symbol and the
modulation system of a transmission digital signal,
outputs a signal indicating the determined modulation
25 system to quadrature baseband modulation section 102 and
outputs a signal indicating the interval of inserting
the determined BPSK modulation symbol to quadrature
baseband modulation section 102, BPSK symbol modulation

section 602 and frame configuration section 104.

BPSK symbol modulation section 602 performs BPSK-modulation on the transmission digital signal at the timing indicated from frame configuration determination section 601 and outputs the in-phase component and the quadrature component of the BPSK modulation symbol to frame configuration section 104.

FIG. 7 illustrates examples of a frame configuration of a signal transmitted from the transmission apparatus of this embodiment and shows a time-symbol relationship. (701) is a frame configuration when the modulation system of information symbols is 16QAM and a BPSK modulation symbol interval is N symbols. (702) is a frame configuration when the modulation system of information symbols is 16QAM and a BPSK modulation symbol interval is M symbols. (703) is a frame configuration when the modulation system of information symbols is 8PSK modulation and a BPSK modulation symbol interval is N symbols. (704) is a frame configuration when the modulation system of information symbols is 8PSK modulation and a BPSK modulation symbol interval is M symbols. Suppose $N < M$ at this time.

Frame configuration determination section 601 selects one of (701), (702), (703) or (704) in FIG.7 as the optimal frame configuration based on the transmission path information and the request data transmission speed information.

For example, in the case of high-speed fading, frame configuration determination section 601 sacrifices data transmission efficiency on the receiving side and selects a frame configuration of either (701) or (703) in FIG.7 so that the interval of inserting a BPSK modulation symbol becomes narrower to prevent deterioration of the data demodulation error rate and maintain the quality of data. On the other hand, in the case of low-speed fading, frame configuration determination section 601 selects a frame configuration of either (702) or (704) in FIG.7 to widen the interval of inserting a BPSK modulation symbol to improve the data transmission efficiency.

Furthermore, when the level of the reception signal is large, frame configuration determination section 601 gives priority to data transmission efficiency on the receiving side and selects a frame configuration of either (701) or (702) in the FIG.7 adopting 16QAM as the modulation system of information symbols. On the other hand, when the level of the reception signal is small, frame configuration determination section 601 gives priority to increasing error resistance while sacrificing data transmission efficiency on the receiving side and selects a frame configuration of either (703) or (704) in FIG.7 adopting 8PSK as the modulation system of information symbols.

FIG.8 shows a signal point layout according to the 16QAM modulation system on the in-phase I - quadrature

Q plane and signal point layout of BPSK modulation symbols. Signal points 801 are the signal points of BPSK modulation symbols and signal points 802 are the signal points of 16QAM modulation symbols. FIG.9 shows a signal point layout according to the 8PSK modulation system on the in-phase I - quadrature Q plane and signal point layout of BPSK modulation symbols. Signal points 901 are the signal points of BPSK modulation symbols and signal points 902 are the signal points of 8PSK modulation symbols.

FIG. 10 is a block diagram showing a configuration of the reception apparatus according to this Embodiment. In the reception apparatus shown in FIG. 10, the components common to the reception apparatus shown in FIG.5 are assigned the same reference numerals as those in FIG.5 and their explanations will be omitted.

In the reception apparatus in FIG.10, transmission path distortion estimation section 1001 differs in the way of operation from transmission path distortion estimation section 503 in FIG.5 and detection section 1002 differs in the way of operation from detection section 504 in FIG.5.

Transmission path distortion estimation section 1001 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, extracts the signals of the BPSK modulation symbols shown in FIG.8 and FIG.9 above, estimates the amount of transmission path distortion from the reception

condition of the BPSK modulation symbols and outputs the amount of transmission path distortion to detection section 1002.

Detection section 1002 receives the in-phase
5 component and the quadrature component of the quadrature baseband signal as inputs, detects information symbols and BPSK modulation symbols based on the amount of transmission path distortion and outputs a reception digital signal.

10 Thus, in this embodiment, by sending information with BPSK modulation symbols, instead of a known pilot symbol, inserted, it is possible to improve the transmission speed compared with Embodiment 1.

Here, this embodiment describes two kinds of the
15 interval of inserting BPSK modulation symbols but the present invention is not limited to this. Also, this embodiment describes two kinds of the modulation system of information symbols, 16QAM and 8PSK modulation, but the present invention is not limited to this.

20 Furthermore, this embodiment describes the frame configuration of only information symbols and BPSK modulation symbols shown in FIG.7 but the present invention is not limited to this frame configuration.

25 (Embodiment 3)

Embodiment 3 describes a digital radio communication method by which the interval of inserting QPSK modulation symbols and the modulation system of

information symbols other than the above QPSK modulation symbols are changed according to the communication situation.

FIG. 11 is a block diagram showing a configuration of the transmission apparatus according to this Embodiment. In the transmission apparatus shown in FIG.11, the components common to those in the transmission apparatus shown in FIG.1 are assigned the same reference numerals as those in FIG.1 and their explanations will be omitted.

In the transmission apparatus in FIG.11, frame configuration determination section 1101 differs in the way of operation from the frame configuration determination section 101 in FIG.1. Also, when compared to FIG.1, the transmission apparatus in FIG.11 adopts a configuration with QPSK symbol modulation section 1102, instead of pilot symbol generation section 103, added.

Frame configuration determination section 1101 judges the communication situation, determines the interval of inserting QPSK modulation symbols and the modulation system of a transmission digital signal, outputs a signal indicating the determined modulation system to quadrature baseband modulation section 102 and outputs a signal indicating the determined interval of inserting QPSK modulation symbols to quadrature baseband modulation section 102, QPSK symbol modulation section 1102 and frame configuration section 104.

QPSK symbol modulation section 1102 performs QPSK-modulation on a transmission digital signal at the timing indicated from frame configuration determination section 1101 and outputs the in-phase component and the quadrature component of the QPSK modulation symbol to frame configuration section 104.

FIG.12 illustrates examples of a frame configuration of a signal transmitted from the transmission apparatus of this embodiment and shows a time-symbol relationship. (1201) is a frame configuration when the modulation system of information symbols is 16QAM and a QPSK modulation symbol interval is N symbols. (1202) is a frame configuration when the modulation system of information symbols is 16QAM and a QPSK modulation symbol interval is M symbols. (1203) is a frame configuration when the modulation system of information symbols is 8PSK modulation and a QPSK modulation symbol interval is N symbols. (1204) is a frame configuration when the modulation system of information symbols is 8PSK modulation and a QPSK modulation symbol interval is M symbols. Suppose $N < M$ at this time.

Frame configuration determination section 1101 selects one of (1201), (1202), (1203) or (1204) in FIG.12 as the optimal frame configuration based on the transmission path information and the request data transmission speed information.

For example, in the case of high-speed fading, frame

configuration determination section 1101 sacrifices data transmission efficiency on the receiving side and selects a frame configuration of either (1201) or (1203) in FIG.12 so that the QPSK modulation symbol insertion interval becomes narrower to prevent deterioration of the data demodulation error rate and maintain the quality of data. On the other hand, in the case of low-speed fading, frame configuration determination section 1101 selects a frame configuration of either (1202) or (1204) in FIG.12 to widen the interval of inserting QPSK modulation symbols to improve the data transmission efficiency.

Furthermore, when the level of the reception signal is large, frame configuration determination section 1101 gives priority to data transmission efficiency on the receiving side and selects a frame configuration of either (1201) or (1202) in FIG.12 adopting 16QAM as the modulation system of information symbols. On the other hand, when the level of the reception signal is small, frame configuration determination section 1101 gives priority to increasing error resistance while sacrificing data transmission efficiency on the receiving side and selects a frame configuration of either (1203) or (1204) in FIG.12 adopting 8PSK as the modulation system of information symbols.

FIG.13 shows a signal point layout according to the 16QAM modulation system on the in-phase I - quadrature Q plane and signal point layout of QPSK modulation

symbols. Signal points 1301 are the signal points of QPSK modulation symbols and signal points 1302 are the signal points of 16QAM modulation symbols. FIG.14 shows a signal point layout according to the 8PSK modulation system on the in-phase I - quadrature Q plane and signal point layout of QPSK modulation symbols. Signal points 1401 are the signal points of QPSK modulation symbols and signal points 1402 are the signal points of 8PSK modulation symbols.

FIG.15 is a block diagram showing a configuration of the reception apparatus according to this embodiment. In the reception apparatus shown in FIG.15, the components common to the reception apparatus shown in FIG.5 are assigned the same reference numerals as those in FIG.5 and their explanations will be omitted.

In the reception apparatus in FIG.15, transmission path distortion estimation section 1501 differs in the way of operation from transmission path distortion estimation section 503 in FIG.5 and detection section 1502 differs in the way of operation from detection section 504 in FIG.5.

Transmission path distortion estimation section 1501 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, extracts the signals of the QPSK modulation symbols shown in FIG.13 and FIG.14 above, estimates the amount of transmission path distortion from the reception condition of the QPSK modulation symbols and outputs the

amount of transmission path distortion to detection section 1502.

Detection section 1502 receives the in-phase component and the quadrature component of the quadrature
5 baseband signal as inputs, detects information symbols and QPSK modulation symbols based on the amount of transmission path distortion and outputs a reception digital signal.

Thus, in this embodiment, by sending information
10 with QPSK modulation symbols, instead of a known pilot symbol, inserted, it is possible to improve the transmission speed compared with Embodiment 1 and Embodiment 2.

Here, this embodiment describes two kinds of the
15 interval of inserting QPSK modulation symbols but the present invention is not limited to this. Also, this embodiment describes two kinds of the modulation system of information symbols, 16QAM and 8PSK modulation, but the present invention is not limited to this.

20 Furthermore, this embodiment describes the frame configuration of only information symbols and QPSK modulation symbols shown in FIG.12 but the present invention is not limited to this frame configuration.

25 (Embodiment 4)

Embodiment 4 describes a digital radio communication method by which the modulation system of information symbols is changed according to the

communication situation and when the modulation system of information symbols uses 8 or more values, a known pilot symbol is inserted with the insertion interval changed according to the communication situation.

5 FIG.16 is a block diagram showing a configuration of the transmission apparatus according to this Embodiment. In the transmission apparatus shown in FIG.16, the components common to those in the transmission apparatus shown in FIG.1 are assigned the
10 same reference numerals as those in FIG.1 and their explanations will be omitted.

 In the transmission apparatus in FIG.16, frame configuration determination section 1601 differs in the way of operation from the frame configuration
15 determination section 101 in FIG.1.

 Frame configuration determination section 1601 determines the modulation system of a transmission digital signal based on the communication situation and outputs a signal indicating the determined modulation
20 system to quadrature baseband modulation section 102. Also, when the determined modulation system uses 8 or more values, frame configuration determination section 1601 determines the interval of inserting a pilot symbol based on the communication situation and outputs a signal
25 indicating the determined interval of inserting the pilot symbol to frame configuration section 104. Also, when the determined modulation system uses 8 fewer values, frame configuration determination section 1601

outputs a signal giving an instruction for stopping the generation of pilot symbols to pilot symbol generation section 103.

Pilot symbol generation section 103 generates a
5 pilot symbol known between the transmitting and
receiving sides and outputs the in-phase component and
the quadrature component of the known pilot symbol to
frame configuration section 104. However, when
10 instructed to stop the generation of pilot symbols from
frame configuration determination section 1601, pilot
symbol generation section 103 stops operation.

FIG.17 illustrates examples of a frame
configuration of a signal transmitted from the
transmission apparatus of this embodiment and shows a
15 time-symbol relationship. (1701) is a frame
configuration when the modulation system of information
symbols is BPSK. (1702) is a frame configuration when
the modulation system of information symbols is QPSK.

The ranking of the frame configurations shown in
20 FIG.2 and FIG.17 in descending order of resistance to
fading speed is (1701), (1702), (203), (201), (204) and
(202). Furthermore, the ranking in descending order of
error resistance is (1701), (1702), (203), (204), (201)
and (202). On the other hand, the ranking in descending
25 order of data transmission efficiency on the receiving
side is (202), (201), (204), (203), (1702) and (1701).

Frame configuration determination section 1601
selects one of (201), (202), (203) or (204) in FIG.2 or

(1701) or (1702) in FIG.17 above as the optimal frame configuration based on the transmission path information and the request data transmission speed information.

FIG.18 shows a signal point layout according to the
5 BPSK modulation method on the in-phase I - quadrature Q plane and signal points 1801 are the signal points of BPSK symbols.

FIG.19 shows a signal point layout according to the
QPSK modulation method on the in-phase I - quadrature
10 Q plane and signal points 1901 are the signal points of QPSK symbols.

FIG. 20 is a block diagram showing a configuration of the reception apparatus according to this embodiment. In the reception apparatus shown in FIG.20, the
15 components common to those in the reception apparatus shown in FIG.5 are assigned the same reference numerals as those in FIG.5 and their explanations will be omitted.

In the reception apparatus in FIG.20, transmission path distortion estimation section 2001 differs in the
20 way of operation from transmission path estimation section 503 in FIG.5 and detection section 2002 differs in the way of operation from detection section 504 in FIG.5.

Transmission path distortion estimation section
25 2001 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, estimates the amount of transmission path distortion from the reception condition of the BPSK modulation

symbol shown in FIG.18 or the QPSK modulation symbol shown in FIG.19 and outputs the amount of transmission path distortion to detection section 2002.

Detection section 2002 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, detects information symbols based on the amount of transmission path distortion and outputs a reception digital signal.

In this way, by changing the modulation system of information symbols according to the communication situation such as fluctuations in the transmission path and the level of the reception signal, inserting a known pilot symbol when the information symbol modulation system is a multi-value modulation system with 8 or more values and changing the interval of inserting the above known pilot symbol according to the communication situation, it is possible to improve both the data transmission efficiency and the quality of data at the same time.

Here, in this embodiment, the transmission apparatus in FIG.16 can also have a configuration equipped with BPSK symbol modulation section 602 shown in FIG.6 instead of pilot symbol generation section 103.

In this case, frame configuration determination section 1601 determines the modulation system of the transmission digital signal based on the communication situation. For example, frame configuration determination section 1601 selects one of (701), (702),

(703) or (704) in FIG.7 above or (1701) or (1702) in FIG.17 as the optimal frame configuration.

Then, frame configuration determination section 1601 outputs the signals indicating the determined modulation system to quadrature baseband modulation section 102. Also, when the determined modulation system uses 8 or more values, frame configuration determination section 1601 determines the interval of inserting BPSK modulation symbols based on the communication situation and outputs a signal indicating the determined interval of inserting the BPSK modulation symbols to BPSK symbol modulation section 602 and frame configuration section 104. Furthermore, when the determined modulation system is 8 fewer values, frame configuration determination section 1601 outputs a signal giving an instruction for stopping the generation of BPSK modulation symbols to BPSK symbol modulation section 602.

BPSK symbol modulation section 602 performs BPSK-modulation on a transmission digital signal at the timing indicated from frame configuration determination section 1601 and outputs the in-phase component and the quadrature component of the BPSK modulation symbols to frame configuration section 104. However, when instructed to stop the generation of BPSK modulation symbols from frame configuration determination section 1601, BPSK symbol modulation section 602 stops operation.

Transmission path distortion estimation section 2001 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, estimates the amount of transmission path distortion from the reception condition of the BPSK modulation symbols shown in FIG.8 and FIG.9 above, the BPSK modulation symbols shown in FIG.18 or the QPSK modulation symbols shown in FIG.19 and outputs the amount of transmission path distortion to detection section 2002.

10 Furthermore, in this embodiment, the transmission apparatus in FIG.16.can also have a configuration equipped with QPSK symbol modulation section 1102 shown in FIG.11 instead of pilot symbol generation section 103.

In this case, frame configuration determination section 1601 determines the modulation system of the transmission digital signal based on the communication situation. For example, frame configuration determination section 1601 selects one of (1201), (1202), (1203) or (1204) in FIG.12 above or (1701) or (1702) in FIG.17 as the optimal frame configuration.

20 Then, frame configuration determination section 1601 outputs a signal indicating the determined modulation system to quadrature baseband modulation section 102. Also, when the determined modulation system uses 8 or more values, frame configuration determination section 1601 determines the interval of inserting QPSK modulation symbols based on the communication situation and outputs a signal indicating

the determined interval of inserting the QPSK symbols to QPSK symbol modulation section 1102 and frame configuration section 104. Also, when the determined modulation system is 8 fewer values, frame configuration determination section 1601 outputs a signal giving an instruction for stopping the generation of QPSK modulation symbols to QPSK symbol modulation section 1102.

QPSK symbol modulation section 1102 performs QPSK-modulation on a transmission digital signal at the timing indicated from frame configuration determination section 1601 and outputs the in-phase component and the quadrature component of the QPSK modulation symbols to frame configuration section 104. However, when instructed to stop generating QPSK modulation symbols from frame configuration determination section 1601, QPSK symbol modulation section 1102 stops operation.

Transmission path distortion estimation section 2001 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, estimates the amount of transmission path distortion from the reception condition of the QPSK modulation symbols shown in FIG.13 or FIG.14 and the BPSK modulation symbols shown in FIG.18 or the QPSK modulation symbol shown in FIG.19 and outputs the amount of transmission path distortion to detection section 2002.

Here, this embodiment explains two kinds of the interval of inserting a known pilot symbol, but the

present invention is not limited to this. Also, this embodiment explains two kinds of the multi-value modulation system with 8 or more values of information symbols, 16QAM and the 8PSK modulation, but the present
5 invention is not limited to this.

Furthermore, this embodiment describes the frame configurations in FIG.2, FIG.7, FIG.12 and FIG.17 but the present invention is not limited to these frame configurations.

10 Furthermore, the BPSK modulation method and the QPSK modulation method of the modulation system of information symbols of the present invention are not limited to the signal point layouts shown in FIG.18 and FIG.19 but $\pi/2$ shift BPSK modulation or $\pi/4$ shift QPSK
15 modulation can also be used.

(Embodiment 5)

Embodiment 5 describes a digital radio communication method by which the interval of inserting
20 a known pilot symbol, the number of signal points with one symbol immediately before and after a known pilot symbol (hereinafter referred to as "symbols before and after a pilot") and signal point layout and the modulation system of information symbols other than those symbols
25 are changed.

FIG.21 is a block diagram showing a configuration of the transmission apparatus according to this embodiment. In the transmission apparatus shown in

FIG.21, the components common to those in the transmission apparatus shown in FIG.1 are assigned the same reference numerals as those shown in FIG.1 and their explanations will be omitted.

5 In the transmission apparatus in FIG.21, frame configuration determination section 2101 differs in the way of operation from frame configuration determination section 101 in FIG.1. Furthermore, the transmission apparatus in FIG.21 adopts a configuration with symbols
10 before and after a pilot modulation section 2102 added compared to FIG.1.

 Frame configuration determination section 2101 determines the interval of inserting a known pilot symbol and the modulation system of a transmission digital
15 signal based on the communication situation. In this case, frame configuration determination section 2101 uses different modulation systems for symbols before and after a pilot and for other information symbols.

 Then, frame configuration determination section
20 2101 outputs a signal indicating the modulation system of symbols before and after a pilot to symbols before and after a pilot modulation section 2102, outputs a signal indicating the modulation system of other information symbols to quadrature baseband modulation
25 section 102 and outputs a signal indicating the interval of inserting the determined known pilot symbol to symbols before and after a pilot modulation section 2102 and frame configuration section 104.

Symbols before and after a pilot modulation section 2102 modulates on a transmission digital signal by predetermined modulation system at the timing indicated from frame configuration determination section 2101 and
 5 outputs the in-phase component and the quadrature component of the symbols before and after a pilot to frame configuration section 104.

FIG.22 illustrates examples of a frame configuration of a signal transmitted from the
 10 transmission apparatus of this embodiment and shows a time-symbol relationship. (2201) is a frame configuration when the modulation system of information symbols is 16QAM and a known pilot symbol interval is N symbols. (2202) is a frame configuration when the
 15 modulation system of information symbols is 16QAM and a known pilot symbol interval is M symbols. (2203) is a frame configuration when the modulation system of information symbols is 8PSK modulation and a known pilot symbol interval is N symbols. (2204) is a frame
 20 configuration when the modulation system of information symbols is 8PSK modulation and a known pilot symbol interval is M symbols. Suppose $N < M$ at this time.

Signal point 2211 is 1 symbol immediately before the known pilot symbol when the information symbol
 25 modulation system is 16QAM and signal point 2212 is 1 symbol immediately after the known pilot symbol when the information symbol modulation system is 16QAM. Signal point 2213 is 1 symbol immediately before the known pilot

symbol when the information symbol modulation system is 8PSK modulation and signal point 2214 is 1 symbol immediately after the known pilot symbol when the information symbol modulation system is 8PSK modulation.

5 Frame configuration determination section 2101 selects one of (2201), (2202), (2203) or (2204) in FIG.22 as the optimal frame configuration based on the transmission path information and the request data transmission speed information.

10 For example, in the case of high-speed fading, frame configuration determination section 2101 sacrifices data transmission efficiency on the receiving side and selects a frame configuration of either (2201) or (2203) in FIG.22 so that the interval of inserting a known pilot
15 symbol becomes narrower to prevent deterioration of the data demodulation error rate and maintain the quality of data. On the other hand, in the case of low-speed fading, frame configuration determination section 2101 selects a frame configuration of either (2202) or (2204)
20 in FIG.22 to widen the interval of inserting a known pilot symbol to improve the data transmission efficiency.

 Furthermore, when the level of the reception signal is large, frame configuration determination section 2101 gives priority to data transmission efficiency on the
25 receiving side and selects a frame configuration of either (2201) or (2202) in FIG.22 adopting 16QAM as the modulation system of information symbols. On the other hand, when the level of the reception signal is small,

frame configuration determination section 2101 gives priority to increasing error resistance while sacrificing data transmission efficiency on the receiving side and selects a frame configuration of either (2203) or (2204) in FIG.22 adopting 8PSK as the modulation system of information symbols.

FIG. 23 shows a signal point layout according to the 16QAM modulation method on the in-phase I - quadrature Q plane and a signal point layout according to a known pilot symbol and a signal point layout of symbols before and after a pilot. Signal point 2301 is the signal point of a known pilot symbol, signal points 2302 are the signal points of 16QAM modulation symbols and signal points 2303 are the signal points of symbols before and after a pilot.

FIG.24 shows a signal point layout according to the 8PSK modulation system on the in-phase I - quadrature Q plane, a signal point layout of a known pilot symbol and a signal point layout of symbols before and after a pilot. Signal points 2401, 2401-A and 2401-B are the signal points of 8PSK modulation symbols, 2401-A is the signal point of the known pilot symbol, 2401-A and 2401-B are the signal points of symbols before and after a pilot and straight line 2402 is the straight line formed by linking the signal point of the known pilot symbol and the origin on the in-phase I - quadrature Q plane.

FIG. 25 is a block diagram showing a configuration of the reception apparatus according to this embodiment.

In the reception apparatus shown in FIG.25, the components common to those in the reception apparatus shown in FIG.5 are assigned the same reference numerals as those shown in FIG.5 and their explanations will be
5 omitted.

In the reception apparatus in FIG.25, transmission path estimation section 2501 differs in the way of operation from transmission path estimation section 503 and detection section 2502 differs in the way of
10 operation from detection section 504 in FIG.5.

Transmission path distortion estimation section 2501 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, extracts the signal of the known pilot symbol shown in
15 FIG.23 and FIG.24 above, estimates the amount of transmission path distortion from the reception condition of the known pilot symbol and outputs the amount of transmission path distortion to detection section 2502.

20 Detection section 2502 receives the in-phase component and the quadrature component of the quadrature baseband signal as inputs, detects information symbols including symbols before and after a pilot based on the amount of transmission path distortion and outputs a
25 reception digital signal.

Thus, changing the interval of inserting a known pilot symbol and the modulation system of information symbols according to the communication situation such

as fluctuations in the transmission path and the level of the reception signal can improve both the data transmission efficiency and the quality of data at the same time.

5 Furthermore, as shown in FIG.23 and FIG.24, by arranging two or more signal points before and after a pilot on the straight line formed by linking the origin and the signal point of the known pilot symbol on the in-phase I - quadrature Q plane, it is possible for the
10 reception apparatus in FIG.25 to suppress deterioration of the estimation accuracy of reference phase and the amount of frequency offset by the pilot symbol, even if symbol synchronization is not established completely when a reference phase and the amount of frequency offset
15 is estimated from the pilot signal. When detection section 116 performs detection, this allows the bit error rate characteristic based on the carrier-to-noise ratio to be improved.

Here, this embodiment can be combined with
20 Embodiment 4 above. That is, when the determined modulation system uses 8 or more values, frame configuration determination section 2101 in FIG.21 determines the interval of inserting a pilot symbol based on the communication situation and outputs a signal
25 indicating the interval of inserting the determined pilot symbol to symbols before and after a pilot modulation section 2102 and frame configuration section 104. Furthermore, when the determined modulation

system uses 8 fewer values, frame configuration determination section 2101 outputs a signal giving an instruction for stopping the generation of pilot symbols to symbols before and after a pilot modulation section 2102 and pilot symbol generation section 103.

Pilot symbol generation section 103 generates a pilot symbol known between the transmitting and receiving sides and outputs the in-phase component and the quadrature component of the known pilot symbol to frame configuration section 104. However, when instructed to stop the generation of pilot symbols from frame configuration determination section 2101, pilot symbol generation section 103 stops operation.

Symbols before and after a pilot modulation section 2102 performs BPSK-modulation or QPSK-modulation on a transmission digital signal at the timing indicated from frame configuration determination section 2101 and outputs the in-phase component and the quadrature component of the symbols before and after a pilot to frame configuration section 104. However, when instructed to stop the generation of pilot symbols from frame configuration determination section 2101, symbols before and after a pilot modulation section 2102 stops operation.

This allows the effect of Embodiment 4 to be attained in addition to the effect of this embodiment as described above.

Here, this embodiment describes two kinds of

modulation system of information symbols, 16QAM and 8PSK modulation, but the present invention is not limited to this.

Furthermore, this embodiment explains only the
5 configuration of information symbols, a known pilot symbol, symbols before and after a pilot in FIG.22, but the frame configuration of the present invention is not limited to the frame configuration composed of only information symbols, a known pilot symbol, symbols
10 before and after a pilot.

As described above, according to the present invention, by changing the interval of inserting a known pilot symbol, BPSK modulation symbols or QPSK modulation symbols and the modulation system of information symbols
15 according to the communication situation of fluctuations in the transmission path and the level of the reception signal, etc., it is possible to improve both the data transmission efficiency and the quality of data at the same time.

20 The present invention is not limited to the above described embodiments, and various variations and modifications may be possible without departing from the scope of the present invention.

This application is based on the Japanese Patent
25 Application No.HEI 11-213289 filed on July 28, 1999, entire content of which is expressly incorporated by reference herein.